



IPIN 2016



SEVENTH INTERNATIONAL CONFERENCE ON
**INDOOR POSITIONING
AND INDOOR NAVIGATION**

October
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Alcalá de Henares, Madrid · Spain



Universidad
de Alcalá

INDEX

PRESENTATION 3

ORGANIZING COMMITTEES 5

DETAILED PROGRAM 9

· Tuesday, 4 October 9

· Wednesday, 5 October 10

· Thursday, 6 October 23

· Friday, 7 October 34

GENERAL INFORMATION 35

PRESENTATION

Welcome to the Seventh International Conference on Indoor Positioning and Indoor Navigation (IPIN2016) and to Alcalá de Henares, a historic town near Madrid. The town of Alcalá de Henares and, principally, the University of Alcalá have earned recognition as a World Heritage Site. Furthermore, the most important award for writers in the Spanish speaking world, the Cervantes Award, is presented annually by the King of Spain in the Paraninfo (Great Hall) of the University of Alcalá in honor of the famous Spanish writer Miguel de Cervantes who was born in Alcalá de Henares and who was the author of Don Quixote.

Since the first edition, IPIN 2010, held in Zurich (Switzerland) with about 450 participants from academia and industry, this Conference has been an excellent forum to bring together researchers, developers and service providers in positioning and indoor navigation. Subsequent editions, held in Guimarães (Portugal), Sydney (Australia), Montbéliard (France), Busan (Korea) and Banff (Canada), also have shown that there is a large and active community working in this sector.

The IPIN2016 Technical Program Committee (TPC) decided to ask for two types of submissions: Regular Papers (limited to 8 double-column pages, preferably for oral presentation) and Work-in-Progress (limited to 4 double-column pages, preferably for poster presentation). 217 contributions were received (151 Regular Papers and 66 Work-in-Progress). Both types of manuscripts followed a peer review process wherein the TPC selected 110 contributions for oral presentation and 61 for poster presentation. The IPIN2016 Technical Program consists of 22 oral sessions and one poster session, covering a broad range of indoor positioning and navigation topics. The Regular Papers presented at the Conference will be submitted to the IEEE Xplore Digital Library, and the authors of both type of papers will have the opportunity to send technically extended versions of conference papers to IEEE Transactions on Instrumentation and Measurement. Best papers will be awarded during the Conference.

In addition, IPIN2016 has its own competition, divided into 4 tracks, with an average of 6 teams per track, with two special sessions dedicated to presentations for competitors. Furthermore, there will be three Plenary Sessions: two keynote speakers, Professor Moe Win (MIT, USA) and Dr. Thomas Burgess (Indoo.rs, Austria); and one Industry Panel, including representatives from seven leading companies in the conference topics (Sonitor Technologies, FAA Airport Engineering Division, ABB Corporate Research, Samsung Electronics R&D Center, Decawave, Bespoon and HERE Tampere).

Without the help of a number of individuals and public and private institutions, this event would never be possible. We are particularly indebted to the University of Alcalá (Departments of International Relations and Research and Innovation, School of Engineering, Department of Electronics) for the facilities and support provided. We would also like to acknowledge and thank the support of our Technical Sponsors (IEEE Geoscience and Remote Sensing Society, IEEE Instrumentation and Measurement Society and IEEE Sección España) and our Competition Sponsors (ETRI, KICS, ASTI and Tecnalia).

The members of the TPC have done a remarkable job in reviewing the papers submitted to the Conference in such a short space of time. Furthermore, IPIN2016 has been made possible thanks to the hard work of the members of the Organizing Committees and the Competition Chairs, to whom we are very grateful.

Finally, we wish to thank you for coming to IPIN2016 - the success of this event will depend on the contribution you make. We hope you will enjoy our Conference and the beautiful town of Alcalá de Henares.

October 2016

Prof. Jesus Ureña and Prof. Kyle O'Keefe
Conference Co-Chairs

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DETAILED PROGRAM

TUESDAY, 4 OCTOBER

09:00 h Registration **North (Blue) Building Hall**

09:30 h On-site competitions (Track 1 and Track 2). **North (Blue) Building Hall**

Competitors should gather at the meeting point for their specific track. The competition will last the whole day.

14:00-19:30 h Tutorials. **Laboratories, first floor, West (Red) Building**

14:00-16:30 h **Tutorial 1:** "Acoustic Positioning Systems", Dr Fernando Álvarez

16:30-17:00 h Coffee Break

17:00-19:30 h **Tutorial 2:** "Fingerprinting-based Indoor Positioning", Dr Raúl Montoliu

14:00 h Track 4 Competition. **North (Blue) Building Hall**

Registration and order of participation draw

14:30-15:15 h Team A

15:15-16:00 h Team B

16:00-16:45 h Team C

16:45-17:30 h Team D

17:30-18:15 h Team E

WEDNESDAY, 5 OCTOBER

08:15 h Registration **North (Blue) Building Hall**

09:00 h **Opening Ceremony. Auditorium**

Keynote. Dr Thomas Burgess, Indoo.rs, Austria. **Auditorium**

“Indoor Navigation: The Crowd is the future - Crowd learning for indoor positioning”

10:00 h Coffee Break

10:30h-12:30 h **Parallel Sessions 1**

A1. Hybrid IMU Pedestrian Navigation & Foot Mounted Navigation (I). Auditorium

Chairperson: Susanna Kaiser

- 58 Using iBeacons for trajectory initialization and calibration in foot-mounted inertial pedestrian positioning systems
Yang Gu, Qian Song, Ming Ma, Yanghuan Li and Zhimin Zhou
- 64 On Monte Carlo Smoothing in Multi Sensor Indoor Localisation
Toni Fetzer, Frank Ebner, Lukas Köping, Marcin Grzegorzec and Frank Deinzer
- 67 Performance Comparison of Foot- and Pocket-Mounted Inertial Navigation Systems
Dina Bousdar, Estefania Munoz Diaz and Susanna Kaiser
- 84 Detecting Elevators and Escalators in 3D Pedestrian Indoor Navigation
Susanna Kaiser and Christopher Lang
- 85 An Anchor based Framework for Trajectory Calibration in Inertial Pedestrian Positioning Systems
Qian Song, Yang Gu, Ming Ma, Yanghuan Li and Zhimin Zhou

B1. User requirements. Room NA5

Chairperson: Lauri Wirola

- 26 User-Friendly Heading Estimation For Various Smartphone Orientations
Phong Nguyen, Takayuki Akiyama and Hiroki Ohashi

- 37 Positioning Evaluation and Ground Truth Definition for Real Life Use Cases
Carlos Martínez de la Osa, Grigorios G. Anagnostopoulos, Mauricio Togneri, Michel Deriaz and Dimitri Konstantas
- 83 Toward Standardized Localization Service
Filip Lemic, Vlado Handziski, Nitesh Mor, Jan Rabaey, John Wawrzynek and Adam Wolisz
- 91 CONE: Zero-Calibration Accurate Confidence Estimation for Indoor Localization Systems
Rizanne Elbakly and Moustafa Youssef
- 161 An Indoor Location Positioning Algorithm for Portable Devices and Autonomous Machines
Farhan Zaki and Rashid Rashidzadeh

C1. Human Motion Monitoring. Room NA6

Chairperson: Marta Marrón

- 69 Pedestrian Motion State Classification using Pressure Sensors
Birendra Ghimire, Christian Nickel and Jochen Seitz
- 108 PIEM: Path Independent Evaluation Metric for Relative Localization
Masaaki Abe, Katsuhiko Kaji, Hiroi Kei and Nobuo Kawaguchi
- 118 An Indoor Self-localization Algorithm Using the Calibration of the Online Geomagnetic Fingerprints and Indoor Landmarks
Qu Wang, Haiyong Luo, Fang Zhao and Wenhua Shao
- 146 Human activity monitoring for falling detection. A realistic framework.
Marcos Baptista-Ríos, Carlos Martínez-García, Cristina Losada-Gutiérrez and Marta Marrón-Romera
- 155 Indoor Localization based on Distance-illumination Model and Active Control of Lighting Devices
Kazuki Moriya, Manato Fujimoto, Yutaka Arakawa and Keiichi Yasumoto

D1. Self-contained sensors. Room NA8

Chairperson: Antoni Pérez-Navarro

- 34 Using Path Matching Filter for Lightweight Indoor Location Determination
Jaroslav Karciarz, Jaroslav Swiatek and Paweł Wilk
- 117 Pedestrian Tracking through Inertial Measurements
Kenneth Hili and Andrew Sammut
- 137 Pedestrian Dead Reckoning with Particle Filter for Handheld Smartphone
Ján Račko, Peter Brida, Arto Perttula, Jussi Parviainen and Jussi Collin
- 151 Hybrid Visual and Inertial Position and Orientation Estimation based on Known Urban 3D Models
Nicolas Antigny, Myriam Servières and Valérie Renaudin
- 154 Fusion system based on WiFi and ultrasounds for In-home Positioning Systems: The UTOPIA Experiment
Sergio Sosa-Sesma and Antoni Pérez-Navarro

E1. Signal Strength Based Methods, Fingerprinting (I). Room NA7

Chairperson: Joaquín Torres-Sospedra

- 25 Domain Clustering Based WiFi Indoor Positioning Algorithm
Wei Zhang, Xianghong Hua, Kegen Yu, Weining Qiu and Shoujian Zhang
- 35 Network-based positioning and pedestrian flow measurement system utilizing densely placed wireless access points
Hiroaki Togashi, Hiroshi Furukawa, Yuki Yamaguchi, Ryuta Abe and Junpei Shimamura
- 51 A Novel Method of WiFi Fingerprint Positioning Using Spatial Multi-points Matching
Wen Li, Dongyan Wei, Hong Yuan and Guangzhou Ouyang
- 59 A Comparative Analysis of Indoor WiFi Positioning at a Large Building Complex
Andreas Mathisen, Søren Krogh Sørensen, Allan Stisen, Henrik Blunck and Kaj Grønbaek

12:00 h Lunch

14:00h-16:00 h

Parallel Sessions 2**A2. Hybrid IMU Pedestrian Navigation & Foot Mounted Navigation (II). Auditorium****Chairperson:** Jörg Blankenbach

- 87 Infrastructureless Indoor Navigation With an Hybrid Magneto-inertial and Depth Sensor System
David Caruso, Martial Sanfourche, Guy le Besnerais and David Vissière
- 93 IMU and Magnetometer Modeling for Smartphone-based PDR
Roland Hostettler and Simo Särkkä
- 111 Near Real Time Heading Drift Correction for Indoor Pedestrian Tracking Based on Sequence Detection
Yang-huan Li, Qian Song, Ming Ma and Yang Gu
- 121 Towards a Robust Smartphone-based 2,5D Pedestrian Localization
Catia Real Ehrlich, Jörg Blankenbach and Arnd Sieprath
- 167 Grid-based indoor localization using smartphones
František Galčík and Miroslav Opiela

B2. UWB (Ultra-wideband). Room NA5**Chairperson:** Fernando Seco

- 21 Ranging in UWB using commercial radio modules: experimental validation and NLOS mitigation
Abbas ghali, Antoni Morell and Jose Lopez Vicario

- 55 Introduction, Discussion and Evaluation of Recursive Bayesian Filters for Linear and Nonlinear Filtering Problems in Indoor Localization
Mathias Pelka and Horst Hellbrück
- 82 Comparing Decawave and Bespoon UWB location systems: indoor/outdoor performance analysis
Antonio R. Jiménez Ruiz and Fernando Seco
- 95 Multi-User Interference and Wireless Clock Synchronization in TDOA-based UWB Localization
Janis Tiemann, Fabian Eckermann and Christian Wietfeld
- 168 A new transmission scheme for wireless synchronization and clock errors reduction in UWB positioning system
Vitomir Djaja-Josko and Jerzy Kolakowski

C2. Optical Systems. Room NA6

Chairperson: Hideo Makino

- 78 DeepMoVIPS: Visual Indoor Positioning Using Transfer Learning
Martin Werner, Carsten Hahn and Lorenz Schauer
- 97 Image-based localization using Gaussian processes
Manuel López-Antequera, Nicolai Petkov and Javier González-Jiménez
- 106 Dual Scaling and Sub-model based PnP Algorithm for Indoor Positioning based on Optical Sensing using Smartphones
Arief Juri, Tughrul Arslan, Yichen Du and Zekun Wang
- 145 QRPos: Indoor Positioning System for Self-Balancing Robots based on QR Codes
Grigori Goronzy, Mathias Pelka and Horst Hellbrück
- 166 Specular Multipath Model for an Optimal Anchor Placement Evolutionary Algorithm
Ernesto Martín Gorostiza, Francisco Domingo-Pérez, José Luis Lázaro-Galilea, Francisco Javier Meca Meca, Andreas Wieser and David Salido-Monzú

D2. Ultrasound systems. Room NA8

Chairperson: Álvaro Hernández

- 77 A Flexible Embedded Hardware Platform Supporting Low-Cost Human Pose Estimation
Dennis Laurijssen, Steven Truijen, Wim Saeys, Walter Daems and Jan Steckel
- 99 High Energy OFDM Pulse Design Algorithm for Acoustic ToF Ranging and Localization
Daniel Albuquerque, José Vieira, Sérgio Lopes, Teodoro Aguilera and Fernando J. Álvarez Franco
- 105 Cooperative Positioning System for Indoor Surveillance Applications
Andrei Stancovici, Mihai Micea and Vladimir Cretu
- 140 Doppler resilient modulation in a CDMA-based Acoustic Local Positioning System
Daniel Albuquerque, José Vieira, Sérgio Lopes, Teodoro Aguilera and Fernando J. Álvarez Franco
- 141 Effect of Parameters of Phase-modulated M-sequence Signal on Direction-of-Arrival and Localization Error
Satoki Ogiso, Takuji Kawagishi, Koichi Mizutani, Naoto Wakatsuki and Keiichi Zempo

E2. Signal Strength Based Methods, Fingerprinting (II). Room NA7

Chairperson: Filipe Meneses

- 89 Position Error and Entropy of Probabilistic Wi-Fi Fingerprinting in the UJIIndoorLoc Dataset
Rafael Berkvens, Maarten Weyn and Herbert Peremans
- 92 Smallest Enclosing Circle-based Fingerprint Clustering and Modified-WKNN Matching Algorithm for Indoor Positioning
Wen Liu, Xiao Fu, Zhongliang Deng, Lianming Xu and Jichao Jiao
- 135 Design of RSSI based fingerprinting with reduced quantization measures
Marouan Mizmizi and Luca Reggiani

16:00-17:30 h

- 152 Combining Multiple Sub-1 GHz Frequencies in Radio Tomographic Imaging
Stijn Denis, Rafael Berkvens, Glenn Ergeerts, Ben Bellekens and Maarten Weyn
- 165 HIPS: Human-based Indoor Positioning System
Andrei Popleteev

Coffee break & **Poster Session & Demos. North (Blue) Building Hall**
Chairpersons: Juan Carlos García, Ana Jiménez and Ernesto Martín

P1. User Requirements

- 184 Towards Prioritised Routing and Effective User Interfaces for a Mobile Shopping Application
Olivier Szymanczyk, Grzegorz Cielniak, Patrick Dickinson, Victoria Lush, Joanna Lumsden, Mike Mannion and Rhys Partlett
- 196 User Interface of Indoor Mapping based on Project TANGO
Holden Li

P2. Hybrid IMU Pedestrian Navigation & Foot Mounted Navigation

- 71 Analysis and Evaluation of a Particle Filter for Wi-Fi Azimuth and Position Tracking
Christian Nickel, Jochen Seitz and Daniel Meister
- 136 C-IPS: a Smartphone based Indoor Positioning System
Federica Inderst, Federica Pascucci and Laura Filardo
- 200 Semi-Automated Calibration of Pedestrian Dead Reckoning Parameters
Thomas Moder, John-Olof Nilsson and Manfred Wieser
- 201 Stance Phase Detection of Multiple Actions for Military Drill Using Foot-mounted IMU
So Young Park, Hojin Ju and Chan Gook Park
- 216 Contextual processing for pedestrian tracking in GPS-denied environments
Enrico de Marinis, Fabrizio Pucci, Michele Uliana, Francesca Fogliuzzi and Fabio Andreucci
- 219 Improvement of Map Matching for Indoor Navigation Exploiting Photo of Information Board
Kento Tonosaki, Yoshihiro Sugaya, Tomo Miyazaki and Shinichiro Omachi

P3. Human Motion Monitoring

- 185 Terminal Profiling for Flow Prediction and Balancing in an Access Network
Saber Mhiri, Jorge Fontenla-Gonzalez, Cristina López Bravo, Francisco J. Gonzalez-Castaño, Felipe Gil-Castiñeira and Carlos Pérez-Garrido
- 197 Symbolic Localization using NILM from only Smart Meter Data
José Alcalá, Jesús Ureña Ureña, Álvaro Hernández and David Gualda
- 204 Measuring Latency in Location Based Services
Casey Baer and Vihang Jani
- 223 Angle of Arrival Estimation using WiFi and Smartphones
Martin Schüssel

P4. High Sensitivity GNSS, Indoor GNSS, Pseudolites

- 53 A GNSS-like Indoor Positioning System Implementing An Inverted Radar Approach Simulation results with a 6/7-antenna single transmitter
Nel Samama, Alexandre Vervisch-Picois and Thierry Taillandier-Loize

P5. Self-contained sensors

- 27 Estimating 3D Pedestrian Trajectories using Stability of Sensing Signal
Katsuhiko Kaji and Nobuo Kawaguchi

P6. Signal Strength Based Methods, Fingerprinting

- 190 Analysis of Nine Vector Distances for Fingerprinting in Multiple-SSID Wi-Fi Networks
Günther Retscher and Julian Joksch
- 206 Weighted Fingerprinting Localization based on a Multichannel WiFi Map
Saehoon Yi and Suk-Yon Kang
- 209 A Study on Distance Estimation Based on Received Signal Strength and Its Cramer-Rao Lower Bound
Masahiro Fujii

- 237 Improved Distance Estimation using a Constellation of RFID Tags
Vighnesh Gharat, Elizabeth Colin, Catherine Marechal and Genevieve Baudoin

P7. UWB (Ultra-wideband)

- 191 Assessment of UWB Ranging Bias in Multipath Environments
Valentin Barral, Pedro Suárez-Casal, Jose A. García-Naya and Carlos J. Escudero
- 210 Trusted Positioning with Two-Way Ranging
Marcel Wagner and Maximilian von Tschirschnitz
- 218 Tracking of Warehouse Forklifts Using an Indoor Positioning System Based on IR-UWB
Huanbang Li, Ryu Miura, Hisashi Nishikawa, Toshinori Kagawa and Fumihide Kojima

P8. Passive & Active RFID

- 213 A New Combination Method of RFID and Geomagnetic Sensor for Indoor Navigation
Seiya Chihara, Bin Sun, Sho Tatsukawa, Tomotaka Wada, Manato Fujimoto and Kouichi Mitsuura
- 221 An RFID-based Real-time Localization of Multiple AGV(Automatic Guided Vehicle) System for the Guided Path Navigation
Youngjae Lee, Jinghong kim, Wonpil Yu and Kiyoun Moon

P9. Optical Systems

- 179 Long Distance VLC-based Beaconing for Indoor Localization Applications
Gergely Zachár, Gergely Vakulya and Gyula Simon
- 198 3D Indoor Positioning and Rapid Data Transfer Technique using Modulated Illumination
Hayato Kumaki, Takayuki Akiyama, Hiromichi Hashizume and Masanori Sugimoto
- 236 Linear Positioning System based on IR Beacon and Angular Detection Photodiode Array
Noriyuki Sakai, Keiichi Zempo, Koichi Mizutani and Naoto Wakatsuki

P10. Ultrasound Systems

- 178 Ultrasound-based orientation and location of mobile nodes combining TOF and RSSI measurements
Carlos Medina, Antonio Bravo, José Carlos Segura, Santiago Medina and Ángel de la Torre
- 193 Ultrasonic Phased Array based on LS Sequences for Reflector Positioning
Cristina Diego, Ana Jiménez and Alvaro Hernández
- 195 Complementary integration of PDR with absolute positioning methods based on time-series consistency
Ryosuke Ichikari, Ching-Tzun Chang, Kenta Michitsuji, Tomoaki Kitagawa, Sota Yoshii and Takeshi Kurata
- 235 Development of an Optoacoustic Distance Measurement System
Bert Cox, Geoffrey Otttoy and Lieven De Strycker

P11. TOF, TDOA based Localization

- 139 Preliminary simulation for an Optical-Indoor Positioning System based on cyclic-Time Difference of Arrival
Angel Enrique Cano García, Yamilet Pompa-Chacón and José Luis Lázaro-Galilea
- 157 Multilateration of the Local Position Measurement
Juri Sidorenko, Norbert Scherer-Negenborn, Michael Arens and Eckart Michaelsen
- 171 Application of phase information for TOA determination in UWB direct conversion receivers
Jerzy Kolakowski
- 173 An OFDM based local positioning system
Robin Theunis, Tuba Ayhan, Nico De Clercq, Paramartha Indirayanti, Tom Redant, Risang Gatot Yudanto, Johan Cockx, Frederik Petré, Patrick Reynaert, Marian Verhelst and Wim Dehaene
- 205 Acoustic Self-Localization for Mobile Robots
Itamar Eliakim, Yossi Yovel and Gabor Kosa

- 211 A TDOA Measurement Technique for Asynchronous Indoor Localization System using UWB-IR
Ankush Vashistha, Rejina Ling Wei Choi and Choi Look Law

P12. Localization, Algorithms for Wireless Sensor Networks

- 156 A Robust Real-Time Indoor Navigation Technique Based on GPU-Accelerated Feature Matching
Jianghua Cheng, Xiangwei Zhu, Wenxia Ding and Gui Gao
- 183 Investigation of Anomaly-based Passive Localization with Received Signal Strength for IEEE 802.15.4
Marco Cimdins, Mathias Pelka and Horst Hellbrück
- 203 Gaussian Processes Model Based Indoor Navigation for Smartphones
Aliaksandr Talochka and Yury Rusovich
- 231 Development of the Indoor Localization System using Fingerprint-based Difference-Means Algorithm in Wi-Fi Environment
Dong Myung Lee and Tae Wan Kim

P14. Mapping, SLAM

- 177 Enhancing Conditional Random Field-based Map Matching with Behavioral Information
Safaa Bataineh, Alfonso Bahillo and Luis Díez
- 180 Work in Progress: Combining Indoor Positioning and 3D Point Clouds from Multispectral Lidar
Sanna Kaasalainen, Simo Gröhn, Olli Nevalainen, Teemu Hakala and Laura Ruotsalainen
- 194 Novel inspection system, backpack-based, for 3D modelling of indoor scenes
Alexandre Filgueira Lago, Susana Lagüela, Pedro Arias and Martín Bueno

P15. Indoor Spatial Data Model & Indoor Mobile Mapping

- 199 Visualization of clusters for indoor positioning based on t-SNE
Pedro E. López-de-Teruel, Óscar Cánovas and Félix J. García

- 214 Improved Active RFID indoor position system by using a RSSI partition criteria based on intervals of confidence to calibrate static signal propagation map
Antonio J. de Vicente, Juan Ramón Velasco, Antonio García and Agustín M. Hellín
- 224 Towards accurate indoor localization using iBeacon, fingerprinting and particle filtering.
Alberto Machi and Giovanni Luca Dierna
- 226 Adaptive Kalman Filter for Indoor Navigation
Boxian Dong and Thomas Burgess

P16. Novel uses of maps and 3D building models

- 207 Calibration of Beacons for Indoor Environments based on a Map-Matching Technique
David Gualda, Jesús Ureña Ureña, Juan Carlos García, José Manuel Alcalá and Alberto Noburu Miyadaira
- 212 Solid image generation for indoor image based positioning. The Bangbae metro station in Seoul
Filiberto Chiabrando, Vincenzo Di Pietra, Andrea Lingua, Juil Jeon and Youngsu Cho
- 215 WiFi FTM and Map Information Fusion for Accurate Positioning
Leor Banin, Yuval Amizur and Uri Schatzberg
- 217 Combining SURF and SIFT for Challenging Indoor Localization using a Feature Cloud
Marvin Ferber, Mark Sastuba and Bernhard Jung

P17. Magnetic Localization

- 134 An Improved RSSI of Geomagnetic Field- Based Indoor Positioning Method Involving Efficient Database Generation by Building Materials
Jinseon Song, Soojung Hur, Yongwan Park and Jeonghee Choi
- 222 Position estimation by means of an magnetometer and Inclinator - An algorithm evaluation
Abdelmoumen Norrdine, Zakari Kasmi and Jörg Blankenbach
- 230 Locating a Magnet in the Near-field
Chao Hu, Zhihuan Zhang, Xiaohe You and Yupeng Ren

P18. Innovative Systems

- 189 2.4 GHz Synthetic Linear Antenna Array for Indoor Propagation Measurements in Static Environments
Stijn Wielandt, Jean-Pierre Goemaere and Lieven De Strycker
- 242 First evaluation of a system of positioning of Microrobot with ultra-dense distribution
Dermas Moffo, Philippe Canalda and François Spies

P19. Applications of Location Awareness & Context Detection

- 176 Location Aware Tracking with Beacons
Gary Mansell and Kevin Curran
- 228 Location-Based Group Clustering Using BLE Beacons in an Unconstrained Indoor Space
Akihiro Sato and Naohiko Kohtake
- 233 A Hybrid Method for Indoor Positioning Based on Wireless Network and Smartphone Camera
Jichao Jiao, Fei Li, Zhongliang Deng and Wen Liu
- 238 GUMUS: a smartguide based on an Acoustic FSK protocol
Fernando J. Álvarez Franco, Teodoro Aguilera, Jorge Morera and José A. Moreno

18:30 h University Welcome & Reception Cocktail.

(Old University building, Plaza de San Diego, city center)

THURSDAY, 6 OCTOBER

08:15 h Registration. **North (Blue) Building Hall**

09:00 h **Keynote. Professor Moe Win.** MIT, USA. **Auditorium**
"Location, location, and location!"

10:00 h Coffee Break

10:30-12:30 h **Parallel Sessions 3**

A3. TOF, TDOA based Localization. Room NA6

Chairperson: Norbert Franke

- 46 Indoor Positioning Using LTE Signals
Marco Driusso, Chris Marshall, Mischa Sabathy, Fabian Knutti, Heinz Mathis and Fulvio Babich
- 76 Firefly Based Distributed Synchronization in Wireless Sensor Networks for Passive Acoustic Localization
Erik Verreycken, Dennis Laurijssen, Walter Daems and Jan Steckel
- 104 Ranging Error Estimation in Indoor Environment at 10 GHz
Camelia Skiribou, Raja Elassali, Fouzia Elbahhar Boukour, Aziz Benlarbi-Delaï, Khalid Elbaamrani and Nouredine Idboufker
- 138 Optimal Microphone Placement for Indoor Acoustic Localization using Evolutionary Optimization
Roberto Macho-Pedroso, Francisco Domingo-Pérez, José Velasco-Cerpa, Cristina Losada-Gutiérrez and Javier Macias-Guarasa
- 160 Android application for indoor positioning of mobile devices using ultrasonic signals
María del Carmen Pérez, David Gualda Gómez, José Manuel Villadangos Carrizo, Jesús Ureña Ureña, Pablo Pajuelo, Edel Díaz LLerena and Enrique García Núñez

B3. Localization, Algorithms for Wireless Sensor Networks. Auditorium

Chairperson: Adriano Moreira

- 41 Smartphone Positioning in Multi-Floor Environments Without Calibration or Added Infrastructure
Simon Burgess, Kalle Åström, Björn Lindquist and Rasmus Ljungberg
- 48 Towards Feasible Wi-Fi based Indoor Tracking Systems Using Probabilistic Methods
Lorenz Schauer, Philipp Marcus and Claudia Linnhoff-Popien
- 107 An Enhanced WiFi Indoor Localization System Based on Machine Learning
Ahmed Salamah, Mohamed Tamazin, Maha Sharkas and Mohamed Khedr
- 123 Wi-Fi probes as digital crumbs for crowd localisation
Francesco Potorti, Antonino Crivello, Michele Girolami, Emilia Traficante and Paolo Barsocchi
- 159 Multilateration Localization Based on Singular Value Decomposition for 3D Indoor Positioning
Jihoon Yang, Haeyoung Lee and Klaus Moessner

C3. Frameworks for Hybrid Positioning. Room NA5

Chairperson: Kyle O'Keefe

- 36 Experimental Evaluation of Visual Place Recognition Algorithms for Personal Indoor Localization
Michal Nowicki, Jan Wietrzykowski and Piotr Skrzypczyński
- 40 A Pipeline Architecture for Indoor Location Tracking
Marcus Dombois and Sebastian Döweling
- 45 IMU/Magnetometer based 3D Indoor Positioning for wheeled Platforms in NLoS scenarios
Hendrik Hellmers, Abdelmoumen Norrdine, Jörg Blankenbach and Andreas Eichhorn
- 112 Comparison of Post-processing Algorithms for Indoor Navigation Trajectories
Kersane Zoubert-Oussen, Christophe Villien and François Le Gland
- 131 RSS-INS Integration for Cooperative Indoor Positioning
Vahid Dehghanian and Matthew Lowe

D3. Mapping, SLAM. Room NA7

Chairperson: Daniel Albuquerque

- 31 Step and activity detection based on the orientation and scale attributes of the SURF algorithm
Chadly Marouane, Andre Ebert, Claudia Linnhoff-Popien and Maximilian Christil
- 65 Dense mapping for Monocular-SLAM
Abiel Aguilar-González and Miguel Arias-Estrada
- 116 A Binary Robust Line Descriptor
Shiwei Zhuang, Danping Zou, Ling Pe,i Di He and Peilin Liu
- 122 Analyzing LiDAR Scan Skewing and its Impact on Scan Matching
Anas Al-Nuaimi, Wilder Lopes, Paul Zeller, Adrian Garcea, Cassio G. Lopes and Eckehard Steinbach
- 174 Reduction of Ultrasonic Indoor Localization Infrastructure based on the use of Graph Information
David Gualda, Jesús Ureña Ureña, Juan Carlos García, José Manuel Alcalá and Alberto N. Miyadira

E3. Other systems and applications. Room NA8

Chairperson: Masanori Sugimoto

- 38 A Spot-controllable Data Transfer Technique Using COTS Speakers
Masanari Nakamura, Takayuki Akiyama, Hiromichi Hashizume and Masanori Sugimoto
- 56 Exploiting Ground Reflection for Robust 3D Smartphone Localization
Joan Bordoy, Johannes Wendeberg, Fabian Höfflinger, Christian Schindelbauer and Leonhard Reindl
- 100 Binarized-BLSTM-RNN based Human Activity Recognition
Marcus Edel, Enrico Köppe and Simon Schmitt
- 102 Fitting for Smoothing: A Methodology for Continuous-Time Target Track Estimation
Tiancheng Li, Javier Prieto and Juan Corchado

- 158 Beacon Placement for Range-Based Indoor Localization
Niranjini Rajagopal, Sindhura Chayapathy, Bruno Sinopoli and Anthony Rowe

12:00 h Lunch

14:00h-16:00 h

Parallel Sessions 4

A4. Novel uses of maps and 3D building models. Room NA5

Chairperson: Fernando Álvarez

- 24 A Low Complexity Map-Aided Fuzzy Decision Tree for Pedestrian Indoor/Outdoor Navigation Using Smartphone
Jhen Kai Liao, Kai Wei Chiang, Guang Je Tsai and Hsiu Wen Chang
- 66 Pedestrian Indoor Navigation for Complex Public Facilities
Olaf Czogalla and Sebastian Naumann
- 70 Anchor Node Placement in Complex Environments with Physical Raytracing and Genetic Algorithms
Tilman Leune, Carsten Koch and Gerd von Cölln
- 115 InLoc: An End-to-End Robust Indoor Localization and Routing Solution using Mobile Phones and BLE Beacons
Vivek Chandel, Nasimuddin Ahmed, Shalini Arora and Avik Ghose
- 129 Conditional Erosion to Estimate Routing Graph out of Floor Plans
Simon Schmitt, Larissa Zech, Thomas Willemsen, Harald Sternberg and Marcel Kyas

B4. Magnetic Localization. Room NA6

Chairperson: Raúl Montoliu

- 75 A Motion Tracking Solution for Indoor Location Using Smartphones
Vânia Guimarães, Lourenco Castro, Susana Carneiro, Manuel Monteiro, Tiago Rocha, Marília Barandas, João Machado, Maria Vasconcelos, Hugo Gamboa and Dirk Elias

- 110 A Heading Error Estimation Approach based on Improved Quasi-static Magnetic Field Detection
Ming Ma, Qian Song, Yang-huan Li, Yang Gu and Zhi-min Zhou
- 119 Magnetic Field based Indoor Positioning Using the Bag of Words Paradigm
Raúl Montoliu, Joaquín Torres-Sospedra and Oscar Belmonte
- 153 Camera-aided Region-based Magnetic Field Indoor Positioning
Yinchen Du, Tughrul Arslan and Arief Juri

C4. Innovative Systems Room NA8

Chairperson: Felipe Espinosa

- 60 Floor vibration type estimation with piezo sensor toward indoor positioning system
Yukitoshi Kashimoto, Manato Fujimoto, Hirohiko Suwa, Yutaka Arakawa and Keiichi Yasumoto
- 81 Mapless Indoor Localization by Trajectory Learning from a Crowd
Jaehyun Yoo, H. Jin Kim and Karl Johansson
- 142 Smart laser scanner for event-based state estimation applied to indoor positioning
Miguel Martínez-Rey, Enrique Santiso, Felipe Espinosa, Rubén Nieto and Alfredo Gardel
- 148 Multipath-Assisted Angle of Arrival Indoor Positioning System in the 2.4 GHz and 5 GHz Band
Stijn Wielandt, Jean-Pierre Goemaere and Lieven De Strycker
- 163 Fusion of Security Camera and RSS Fingerprinting for Indoor Multi-Person Tracking
Christopher Nielsen, John Nielsen and Vahid Dehghanian

D4. Applications of Location Awareness & Context Detection. Room NA7

Chairperson: Elizabeth Colin

- 29 Online Self-Calibration of the Propagation Model for Indoor Positioning Ranging Methods
Grigorios G. Anagnostopoulos, Michel Deriaz and Dimitri Konstantas

- 32 Visual Odometry using motion vectors from visual feature points
Chadly Marouane, Marco Maier, Alexander Leupold and Claudia Linnhoff-Popien
- 79 Indoor Positioning of Shoppers Using a Network of Bluetooth Low Energy Beacons
Patrick Dickinson, Greg Cielniak, Olivier Szymanczyk and Mike Mannion
- 132 Location Awareness Enables Autonomous Commissioning in Wireless Sensor Networks
Stijn Crul, Geoffrey Ottoy and Lieven De Strycker
- 164 Optimal Placement of Landmarks for Indoor Localization using Sensors with a Limited Range
Payam Nazemzadeh, Daniele Fontanelli and David Macii

E4. Competition Presentations (I). Auditorium

Track 1. Smartphone-based.

Chairpersons: Paolo Barsocchi and Michele Girolami

Team # Work description and team members

- 1 Multi Sensor Indoor Localisation
Toni Fetzer, Frank Ebner, Frank Deinzer and Marcin Grzegorzek
- 2 Integrating Wi-Fi and Magnetic Field for Fingerprinting Based Indoor Positioning System
Yuntian Brian Bai, Tao Gu and Andong Hu
- 3 Navix: Smartphone Based Hybrid Indoor Positioning
J. C. Aguilar Herrera and A. Ramos
- 4 WiMag: Multimode Fusion Localization System based on Magnetic/WiFi/PDR
Haiyong Luo, Qu Wang, Wenhua Shao, Dongmeng Li, Xumeng Guo and Fang Zha
- 5 A Real-time Indoor Tracking System by Fusing Inertial Sensor, Radio Signal and Floor Plan
José Luis Carrera, Zhongliang Zhao, Torsten Braun and Zan Li

- 6 Hand-held Indoor Positioning System Based On Smartphone
Lingxiang Zheng, Yizhen Wang, Ao Peng, Zongheng Wu, Shaolin Wen, Biyu Tang, Hai Lu, Haibin Shi and Huiru Zheng

Track 3. Smartphone-based (off-site)

Chairpersons: Joaquín Torres and Fernando Seco

Team # Work description and team members

- 1 WiFi Fingerprinting using Bayesian and Hierarchical Supervised Machine Learning assisted by GPS
Yair Beer
- 2 Smartphone-based User Location Tracking in Indoor Environment
Viet-Cuong Ta, Dominique Vaufreydaz, Dao Trung Kien and Eric Castelli
- 3 Indoor tracking from multidimensional sensor data
Adriano Moreira, Maria João Nicolau, António Costa and Filipe Meneses
- 4 Multi Sensor Indoor Localisation
Toni Fetzer, Frank Ebner, Frank Deinzer and Marcin Grzegorzek
- 5 Smartphone positioning in large environments by sensor data fusion, particle filter and FCWC
Stefan Knauth and Athanasios Koukofikis

16:00 h Coffee break

16:30h-18:30 h **Parallel Sessions 5**

B5. High Sensitivity GNSS, Indoor GNSS, Pseudolites. Room NA5

Chairperson: Andreas Wieser

- 44 Sensitivity of Projection-Based Near-Far Mitigation Techniques in High-Sensitivity GNSS Software Receivers
Sergi Locubiche-Serra, José A. López-Salcedo and Gonzalo Seco-Granados

- 52 A GNSS-based Inverted Radar for Carrier Phase Absolute Indoor Positioning Purposes First experimental results with GPS signals
Nel Samama, Alexandre Vervisch-Picois and Thierry Taillandier-Loize
- 61 A Combined Approach of Doppler and Carrier-based Hyperbolic Positioning with a Multi-channel GPS-pseudolite for Indoor Localization of Robots
Kenjiro Fujii, Ryosuke Yonezawa, Yoshihiro Sakamoto, Alexander Schmitz and Shigeki Sugano
- 63 Delta Carrier Range Algorithm for Indoor Positioning Application to Pseudolite-like Transmitters
Alexandre Vervisch and Nel Samama
- 170 Innovative Techniques for Collective Detection of Multiple GNSS Signals in Challenging Environments
Maherizo Andrianarison, Mohamed Sahmoudi and René Jr Landry

C5. Passive & Active RFID. Room NA6

Chairperson: Günther Retscher

- 47 Positioning using ambient magnetic fields in combination with Wi-Fi and RFID
Andreas Ettliger and Günther Retscher
- 90 Low-Complexity PDoA-based Localization
Benjamin Sackenreuter, Niels Hadaschik, Marc Faßbinder and Christopher Mutschler
- 113 A Survey of Problems and Approaches in Wireless-based Indoor Positioning
Felis Dwiyasa and Meng-Hiot Lim
- 125 RFID-based centralized cooperative localization in indoor environments
Fernando Seco, Antonio R. Jiménez Ruiz and Xufei Zheng
- 144 Full-scale Testing and Performance Evaluation of an Active RFID System for Positioning and Personal Mobility
Vassilis Gikas, Guenther Retscher, Andreas Ettliger, Harris Perakis and Andreas Dimitratos

D5. Indoor Spatial Data Model & Indoor Mobile Mapping. Room NA7

Chairperson: Valérie Renaudin

- 54 Easing the Survey Burden: Quantitative Assessment of Low-Cost Signal Surveys for Indoor Positioning
Chao Gao and Robert Harle
- 72 Door Detection in 3D Colored Laser Scans for Autonomous Indoor Navigation
Blanca Quintana, Samuel A. Prieto, Antonio Adán and Frédéric Bosché
- 73 A multisource and multivariate dataset for indoor localization methods based on WLAN and geomagnetic field fingerprinting
Paolo Barsocchi, Antonino Crivello, Davide La Rosa and Filippo Palumbo
- 127 Accurate Indoor Georeferencing with Kinematic Multi Sensor Systems
Sören Vogel, Hamza Alkhatib and Ingo Neumann
- 143 A multi-hypothesis particle filtering approach for pedestrian dead reckoning
Fadoua Taia Alaoui, David Betaille and Valerie Renaudin

E5. Competition Presentations (II). Auditorium

Track 2. Pedestrian dead reckoning positioning

Chairpersons: Soyeon Lee and Jae Hyun Lim

Team # Work description and team members

- 1 Motion estimation of a Rigid Body with an EKF using Magneto-Inertial Measurements
Charles-Ivan Chesneau, Mathieu Hillion and Christophe Prieur
- 2 Foot Mounted Inertial Navigation System using Estimated Velocity During the Contact Phase
Hojin Ju, So Young Park and Chan Gook Park.

- 3 Foot-mounted indoor Pedestrian Positioning System based on Low-cost Inertial Sensors
Ao Peng, Lingxiang Zheng, Wencheng Zhou, Chaohui Yan, Yizhen Wang, XiaoYang Ruan, Biyu Tang, Haibin Shi, Hai Lu and Huiru Zheng
- 4 Pedestrian Positioning from Wrist-worn Wearable Devices
Luis Enrique Díez and Alfonso Bahillo
- 5 A Multifloor Hybrid Inertial/Barometric Navigation System
Nicolò Strozzi, Federico Parisi and Gianluigi Ferrari
- 6 Accurate Dual-foot Micro-inertial Navigation System with Inter-agent Ranging
ZhouLing Xiao, YiZhuo Yang, Rui Mu and JianBo Liang
- 7 D-ZUPT based Pedestrian Dead-Reckoning System Using Low Cost IMU
Yu Liu, Kai Guo and Shenglong Li
- 8 3D Pedestrian Dead Reckoning Based on Kinematic Models in Human Activity by Using Multiple Low-Cost IMUs
Jihoon Yang, Haeyoung Lee and Klaus Moessner

Track 4. Indoor mobile robot positioning

Chairpersons: María C. Pérez and Cristina Losada

Team # Work description and team members

- 1 ATLAS - An Open-Source TDOA-based Ultra-Wideband Localization System
Janis Tiemann, Fabian Eckermann and Christian Wietfeld
- 2 Aidloc: A high acoustic smartphone indoor localization system with NLOS identification and mitigation
Zhi Wang, Lei Zhang, Feng Lin and Danjie Huang
- 3 Indoor Localization using Visible Light
Siu Wai Ho

19:30h-20:30 h
20:30 h

- 4 TOPOrtIs TPM UWB wireless system technical description
Maksim Katkov and Sergey Huba
 - 5 Technical description of Locate-US: an Ultrasonic Local Positioning System based on Encoded Beacons. **(Out of Competition)**
J. Ureña, J. M. Villadangos, D. Gualda, M. C. Pérez, A. Hernández, J. J. García, A. Jiménez, J. C. García, J. F. Arango and E. Díaz
- Alcalá de Henares visit. **(From Plaza Cervantes, city center)**
Gala Dinner. **(Restaurant Hostería del Estudiante, city center)**
Attendees can enjoy a live “Flamenco Show” after Gala Dinner in “Aula de Música” (c/ Colegios 10, city center) (estimated duration 45 minutes)

FRIDAY, 7 OCTOBER

9:00 h **Industry Panel. Auditorium**

Moderator: Fernando Álvarez, University of Extremadura, Spain

Speaker

Company

Dr Wilfred E. Booij

Sonitor Technologies, Norway

Nayeem Hoq

FAA Airport Engineering Division, USA

Linus Thrybom

ABB Corporate Research, Sweden

Pawel Wilk

Samsung Electronics R&D Center, Poland

Mickael Viot

Decawave Vice President of Marketing, Ireland

Pascal Fabré

Bespoon, France

Dr Lauri Wirola

HERE Tampere, Finland

10:15 h Coffee Break

10:45 h **Best papers presentation. Auditorium**

12:00 h **Competition Awards Ceremony. Auditorium**

13:00 h **Closing Ceremony & IPIN2017 Presentation. Auditorium**

13:30 h Farewell Cocktail. **North (Blue) Building Hall**

GENERAL INFORMATION

A. CONFERENCE VENUE

The Conference will be held in the Escuela Politécnica (School of Engineering) of the University of Alcalá, Campus Universitario de la Universidad de Alcalá, carretera Madrid-Barcelona, km. 33,600. It is located within 20 minutes by bus distance from the city centre and from most hotels. Most of Conference activities are organized in the North Building (blue area).

B. REGISTRATION

The Registration Desk is located in the hall of the North Area at the Escuela Politécnica (School of Engineering).

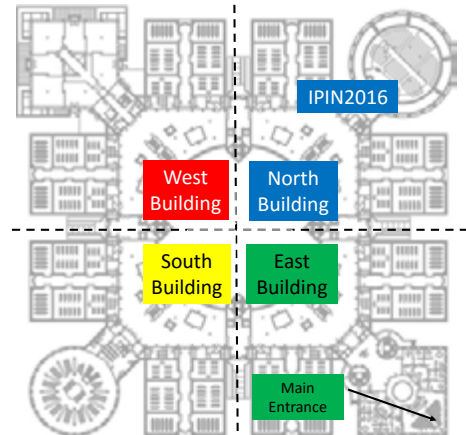
Opening hours:

Tuesday, 4th October: 09:00 - 12:00h

Wednesday, 5th October: 08:15 - 12:30 and 13:30 - 17:30 h.

Thursday, 6th October: 08:15 - 12:30 and 13:30 - 18:30 h.

Friday, 7th October: 08:30 - 13:30



C. PRESENTATIONS

1. ORAL PRESENTATIONS

Each oral presentation will last 22 minutes, including 4-5 minutes for questions. We recommend you prepare your slides (including all media data needed) for a duration of 17-18 minutes. Each presentation room will be equipped with a video projector with a VGA connector and a Windows laptop with PowerPoint and Adobe Acrobat Reader. Please remind to embed all fonts in your presentation files. All authors should load their presentations during the break preceding their presentation sessions.

The Conference Program is organized in parallel sessions, and they will be held in different rooms (North building – blue area):

- **Plenary Sessions Room - Auditorium:** Keynotes; Sessions A1, A2, B3, E4 and E5; Industry Panel; Best Papers Presentation; Competition Awards Ceremony and Closing Ceremony.
- **Room NA5:** Sessions B1, B2, C3, A4 and B5
- **Room NA6:** Sessions C1, C2, A3, B4 and C5
- **Room NA7:** Sessions E1, E2, D3, D4 and D5
- **Room NA8:** Sessions D1, D2, E3 and C4

2. POSTER SESSION

Posters can be displayed on Wednesday morning. Presenting authors should be close to their posters during the whole Poster Session (Wednesday afternoon, 16:00h-17:30h). If the authors wish, poster can keep displayed until Friday, 7th October.

Poster board dimensions are enough for a DINA0 portrait poster (84.1cmx118.9cm).

D. LUNCHES, COFFEE BREAKS AND BANQUET

Lunches and coffee services will be provided free of charge from Wednesday to Friday for the registered attendees.

Coffee breaks will be held in the courtyard of the Escuela Politécnica (School of Engineering) and **Lunches** in the cafeteria. Both of them will be served according to the Conference Program timetable.

Finally, the **Gala Dinner** will be held in Hostería del Estudiante (c/ Colegios, 3), at 20:30 on Thursday, 6th October. A limited number of extra tickets for non-registered attendees will be available for being purchased at the Registration Desk.

E. INTERNET ACCESS

Internet access will be available at Room OA.5 (Computer Room) in the Escuela Politécnica (School of Engineering). The Conference Organization will provide three laptops for the registered participants.

Free WIFI will be also available at the building:

- SSID Name: congresos
- Password: UAHcongresos2016

F. GUIDED VISITS

- Ancient building of the University of Alcalá (Rectorado). The visit will be held on Wednesday, 5th October at 18:30h. Meeting point: city center, Plaza de San Diego (San Diego square).
- Alcalá de Henares Old City Center. The visit will be held on Thursday, 6th October at 19:30h. **Meeting point:** city center, Plaza de Cervantes (Cervantes square), statue of “Miguel de Cervantes” (center of the square).



Alcalá de Henares, City Center



Escuela Politécnica
School of Engineering
(Ground Floor)



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