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**Record 1 of 1****Title:** Improving the Efficiency of Highly Predictable Wireless Sensor Platforms With Hybrid Scheduling**Author(s):** Micea, MV (Micea, Mihai V.); Stangaciu, CS (Stangaciu, Cristina S.); Stangaciu, V (Stangaciu, Valentin); Cretu, VI (Cretu, Vladimir I.)**Book Group Author(s):** IEEE**Source:** 2012 IEEE INTERNATIONAL SYMPOSIUM ON ROBOTIC AND SENSORS ENVIRONMENTS (ROSE 2012) **Pages:** 73-78 **Published:** 2012**Times Cited in Web of Science:** 0**Total Times Cited:** 0**Cited Reference Count:** 16**Abstract:** We focus on increasing the execution efficiency and flexibility of fully predictable embedded platforms, with direct applications in wireless sensor networks. The proposed technique is a hybrid scheduling mechanism, which combines the high predictability of a non-preemptive cyclic scheduler with the efficiency of a modified version of the Earliest Deadline First algorithm. Implementation details on ARM7-based platforms are provided, along with a case study of real-time wireless communication driver for sensor networks. The experimental results prove that this method achieves the proposed goals: an increased execution efficiency and flexibility while preserving the required real-time predictability of the systems.**Accession Number:** WOS:000335755600012**Language:** English**Document Type:** Proceedings Paper**Conference Title:** 10th IEEE International Symposium on Robotic and Sensors Environments (ROSE)**Conference Date:** NOV 16-18, 2012**Conference Location:** Magdeburg, GERMANY**Conference Sponsors:** Inst Elect & Elect Engineers, IEEE Instrumentat & Measurement Soc, IMS TC 15 Virtual Syst Measurements, IMS TC 22 Intelligent Measurement Syst, IMS TC 27 Human Comp Interface & Interact, IMS TC 28 Instrumentat Robot & Automat, IMS TC-30 Secur & Contraband Detect**Conference Host:** Otto von Guericke Univ**Author Keywords:** Hard real-time (HRT); hybrid scheduling; predictability; smart sensors; wireless communication**Addresses:** [Micea, Mihai V.; Stangaciu, Cristina S.; Stangaciu, Valentin; Cretu, Vladimir I.] Politehn Univ Timisoara, Comp & Software Engn Dept, Timisoara 300223, Romania.**Reprint Address:** Micea, MV (reprint author), Politehn Univ Timisoara, Comp & Software Engn Dept, 2 Vasile Parvan Blvd, Timisoara 300223, Romania.**E-mail Addresses:** mihai.micea@cs.upt.ro; certejan@dsplabs.cs.upt.ro; valys@dsplabs.cs.upt.ro; vladimir.cretu@cs.upt.ro**Publisher:** IEEE**Publisher Address:** 345 E 47TH ST, NEW YORK, NY 10017 USA**Web of Science Categories:** Engineering, Electrical & Electronic; Robotics**Research Areas:** Engineering; Robotics**IDS Number:** BA4HY**ISBN:** 978-1-4673-2704-6**Source Item Page Count:** 6

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